

1. Study HW Problems 1-5 in Section 3.1 - 2nd Order Linear Homogeneous constant coefficients - Real distinct roots
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/RealRoots.aspx>
2. Study HW Problems 1-4 in Section 3.2 - General Solution Theorem - the Wronskian
3. Study HW Problems 1-2 in Section 3.3 - 2nd Order Linear Homogeneous constant coefficients - complex roots
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/ComplexRoots.aspx>
4. Study HW Problems 1-3 in Section 3.4.1 - 2nd Order Linear Homogeneous constant coefficients - Real repeated roots
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/RepeatedRoots.aspx>
5. Study HW Problems 1-4 in Section 3.4.2 - Method of Reduction of Order
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/ReductionofOrder.aspx>
6. Study HW Problems 1-7 in Section 3.5 - non-homogeneous equations - MOUC
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/NonhomogeneousDE.aspx>
7. Study HW Problems 1-4 in Section 3.6 - non-homogeneous equations - Variation of Parameters
 - For more Sample Problems with solutions:
 - Click here: <http://tutorial.math.lamar.edu/Classes/DE/VariationofParameters.aspx>
8. Study HW Problems 1-4 in Section 3.7 - Mechanical and Electrical Vibrations
 - For more Sample Problems with solutions:
 - <http://tutorial.math.lamar.edu/Classes/DE/Vibrations.aspx>
9. Study HW Problems 1-6 in Section 4.1 - Higher Order Systems - homogeneous
 - For more Sample Problems with solutions:
 - <http://tutorial.math.lamar.edu/Classes/DE/HOHomogeneousDE.aspx>
10. Study HW Problems 1-4 in Section 4.2 - Higher Order Systems - non-homogeneous
 - For more Sample Problems with solutions:
 - <http://tutorial.math.lamar.edu/Classes/DE/HOUndeterminedCoeff.aspx>
11. Study only HW Problem 3 in Section 6.1 - Intro to Laplace Transforms
 - For more Sample Problems with solutions:
 - <http://tutorial.math.lamar.edu/Classes/DE/LaplaceTransforms.aspx>

Formula Sheet

• General Solution Theorem for Homogeneous Equations:

Theorem 1 (General Solution Theorem) Suppose y_1 and y_2 are two solutions to the ODE

$$y'' + p(t)y' + q(t)y = 0$$

in some interval I , where p, q are continuous. Then the family of solutions

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

for arbitrary c_1, c_2 is the **general solution** (meaning includes every solution to the ODE) if and only if the Wronskian $W(y_1, y_2)$ is not zero for at least one point t_0 in I .

• Variation of Parameters:

Theorem 2 (Variation of Parameters) If p, q , and g are continuous on an open interval I , and if the functions $\{y_1, y_2\}$ form a fundamental set of solutions to the corresponding homogeneous EQ

$$y'' + p(t)y' + q(t)y = 0.$$

Then a particular solution to

$$y'' + p(t)y' + q(t)y = g(t),$$

is given by

$$\begin{aligned} y_p(t) &= -y_1(t) \int_{t_0}^t \frac{y_2(s)g(s)}{W(y_1, y_2)(s)} ds + y_2(t) \int_{t_0}^t \frac{y_1(s)g(s)}{W(y_1, y_2)(s)} ds \\ &= -y_1(t) \left[\int \frac{y_2(t)g(t)}{W(y_1, y_2)(t)} dt \right] + y_2(t) \left[\int \frac{y_1(t)g(t)}{W(y_1, y_2)(t)} dt \right], \text{ if an antiderivative exists} \end{aligned}$$

where t_0 is any value in I . Then **general solution** to the non-homogeneous solution is

$$y(t) = c_1y_1(t) + c_2y_2(t) + y_p(t).$$

• Motion of a spring:

- The motion of $u(t)$ is modeled by the following:

$$mu''(t) + \gamma u'(t) + ku(t) = F(t) \quad u(0) = u_0, u'(0) = v_0.$$

where m, γ, k are positive.

- m is found from $w = mg$
- γ is given in units of $\frac{\text{weight unit} \cdot \text{s}}{\text{distance unit}}$.
- k is found using Hooke's Law, $mg = kL$

- **(Existence and Uniqueness Theorem for n Order Linear ODEs):** If the functions p_1, \dots, p_{n-1} and g are continuous on an open interval $I = (a, b)$ containing the point $t = t_0$, then there **exists** a **unique** function $y = \phi(t)$ that satisfies the IVP

$$y^{(n)} + p_{n-1}(t)y^{(n-1)} + \dots + p_1(t)y' + p_0(t)y = g(t). \quad (\star)$$

with initial conditions

$$y(t_0) = y_0, y'(t_0) = y'_0, \dots, y^{(n-1)}(t_0) = y_0^{(n-1)}. \quad (\star)$$

for each t in I .

	$f(t) = \mathcal{L}^{-1}\{F(s)\}$	$F(s) = \mathcal{L}\{f(t)\}$
1.	1	$\frac{1}{s}$
2.	e^{at}	$\frac{1}{s-a}$
3.	t^n	$\frac{n!}{s^{n+1}}$
4.	t^p ($p > -1$)	$\frac{\Gamma(p+1)}{s^{p+1}}$
5.	$\sin at$	$\frac{a}{s^2+a^2}$
6.	$\cos at$	$\frac{s}{s^2+a^2}$
7.	$\sinh at$	$\frac{a}{s^2-a^2}$
8.	$\cosh at$	$\frac{s}{s^2-a^2}$
9.	$e^{at} \sin bt$	$\frac{b}{(s-a)^2+b^2}$
10.	$e^{at} \cos bt$	$\frac{s-a}{(s-a)^2+b^2}$
11.	$t^n e^{at}$	$\frac{n!}{(s-a)^{n+1}}$
12.	$u_c(t)$	$\frac{e^{-cs}}{s}$
13.	$u_c(t)f(t-c)$	$e^{-cs}F(s)$
14.	$e^{ct}f(t)$	$F(s-c)$
15.	$f(ct)$	$\frac{1}{c}F\left(\frac{s}{c}\right), c > 0$
16.	$\int_0^t f(t-\tau)g(\tau) d\tau$	$F(s)G(s)$
17.	$\delta(t-c)$	e^{-cs}
18.	$f^{(n)}(t)$	$s^n F(s) - s^{n-1}f(0) - \dots - sf^{(n-2)}(0) - f^{(n-1)}(0)$
19.	$(-t)^n f(t)$	$F^{(n)}(s)$